

BLASTMAN B20C-S

ROBOT CONFIGURATION

		Range /m/°	Max. Speed	Type
Axis 1	Robot bridge longitudinal	5 - 100 m	0,3 m/s	Lin.
Axis 2	Arm carriage across	3 - 35 m	0,25 m/s	Lin.
Axis 3	Rotation of the telescope	360°	18,7 °/s	Rot.
Axis 4	Arm vertical (Telesc.)	2 - 6 m	0,26 m/s	Lin.
Axis 5	Shoulder	175°	21,5°/s	Rot.
Axis 6	Elbow	225°	19,9°/s	Rot.
Axis 7	Arm head	360°	180°/s	Rot.
Axis 8	Nozzle	270°	215 °/s	Rot.
Axis 9	Cabin bridge	5 - 100 m	0,3 m/s	Lin.
Axis 10	Cabin carriage	3 - 35 m	0,25 m/s	Lin.
Axis 11	Cabin telescope Rotation	360°	20°/s	Rot.
Axis 12	Cabin telescope	2 - 6 m	0,26 m/s	Lin.

OPERATION MODES

Manual
Automatic
Parameter based automatic

TEACHING METHODS

Teach In
PTP (option)
Offline (option)
Parameter based (option)

OPERATIONAL PARAM.

Nozzle diam. 6 - 19 mm
Nozzle diam. 1/4" - 3/4"
No. Of Nozzles 1 or 2
Air Pressure 4 - 11 bar
Air Pressure 50 - 150 PSI
Cleaning rate200 m²/h
Cleaning rate2150 ft²/h

TECHNICAL

Voltage 380-500V 50/60Hz
Contr. voltage 24 VDC
Sealing * IP65
Assembly Roof Mounted
Weight ** 10 000 kg

*Applies to electrics in the blast room

** Depends on width

FEATURES

Control

- License for software updates
- Offline teaching
- VPN connection for remote diagnosis and SW updates
- Mobile monitoring
- Control of blast room machineries

Convenience

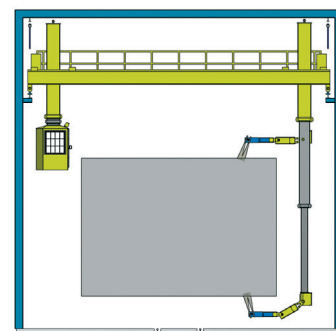
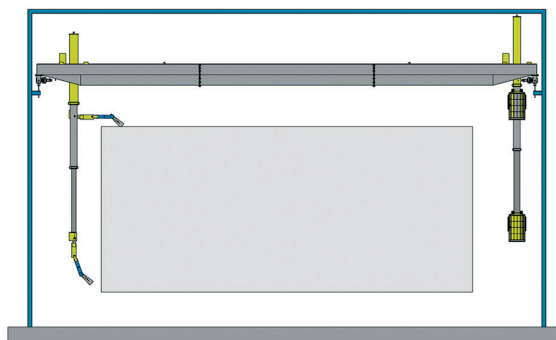
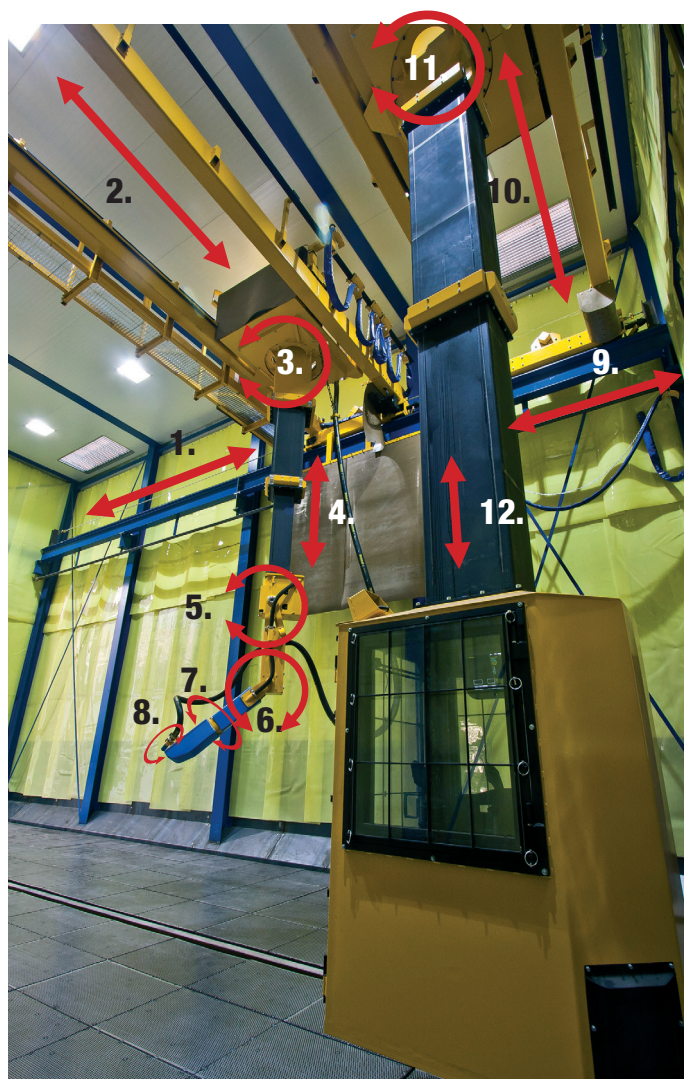
- AC in Control cabin
- Radio in Control cabin

Blast equipment

- Complete operational blast room
- Blast pot for robot
- Blast hose
- Blast nozzles

Other

- Rails for the robot
- Transfer car for the workpiece
- Warranty extension
- Installation services



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